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RNA VELOCITY EMBEDDINGS IN CURVED SPACES

EXPLORING CELLULAR DYNAMICS

From single cells to populations

joint w/

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Gene Expression

From code to function

- DNA \rightarrow mRNA \rightarrow proteins
- gene expression \simeq # mRNA snippets
- proxy for cell's current biological state $x_i \in \mathbb{R}^N$

Population Dynamics

La Manno, G. et al. (2018) 'RNA velocity of single cells', Nature, 560(7719), pp. 494–498. Fig 2.

Model schematic

Danciu, D.-P. et al. (2023) 'Mathematics of neural stem cells: Linking data and processes', Cells & Development, 174, p. 203849. Fig 1 & Fig 5A.

"Standard" RNA velocity *La Manno, G. et al. (2018) 'RNA velocity of single cells', Nature, 560(7719), pp. 494–498. Fig 1.*

 $\mathbf{v}_i \in \mathbb{R}^N$ RNA velocity

"Standard" Visualizations

Given RNA-velocity data

$$
(x_i, v_i) \in \mathbb{R}^N \times \mathbb{R}^N
$$

1. get low dimensional representation

 $x_i \mapsto y_i \in \mathbb{R}^2$

2. "pushforward" of velocities $v_i \mapsto w_i \in \mathbb{R}^2$ st.

Similarity $(v_i, x_j - x_i) \simeq$ Similarity (w_i)

, y^j − *yi*) *La Manno, G. et al. (2018) 'RNA velocity of single cells', Nature, 560(7719), pp. 494–498. Fig 2.*

Common Criticism of "standard" approach

RNA velocities *vⁱ* are not tangent to data manifold.

Manifold Constrained RNA Velocity

- 1. Choose cell-state manifold M (e.g. $M = S^1$)
- 2. Assume gene expressions depend only on *M*
- 3. compute representation of scRNA-seq data in *M* (t) hink: coordinization $x(y)$, $s(y)$, $u(y)$)
- 4. infer RNA velocity in low-dimensional representation
- 5. (optional) pull velocities back to \mathbb{R}^N for downstream analysis

$$
\left(\nabla_x s_g\right)\cdot V\big(x(t)\big)=\beta_g u_g\big(x(t)\big)-\gamma_g s_g\big(x(t)\big)
$$

Lederer, A.R. et al. (2024) 'Statistical inference with a manifold-constrained RNA velocity model uncovers cell cycle speed modulations'.

Successfully tested for cell cycle. RNA velocities generally point in the expected direction (and show interesting speed modulations).

Taking a step back

"Standard" position and velocity pairs are points in tangent bundle (aka phase space)

$$
(x_i, v_i) \in \mathbb{R}^N \times \mathbb{R}^N = T\mathbb{R}^N
$$

1. Manifold assumption

Data is noisy sample from $TM \hookrightarrow T\mathbb{R}^N$ \rightarrow low-dim representations in tangent bundles

2. "Geometric Dynamics" assumption

Time evolution is determined by flow on *TM* \rightarrow can flows in dimensionally reduced representation capture principal dynamical components?

Note: This kind of data is ubiquitous

- Meteorology (pressure and wind velocity)
- Astronomy (space velocity of stars)
- Velocity Obstacle Problem in robotic motion planning
- Traffic Flow Dynamics (often includes acceleration \rightsquigarrow (x_i, v_i, a_i) ∈ J^2M second Jet bundle)

The Sasaki Metric

(*M, g*) – Riemannian manifold.

Naturally induced Sasaki Metric on *TM*

∃ 2-parameter family of natural metrics

$$
g_{\text{Sasaki}} = g \oplus g : T(TM) \simeq \underbrace{TM}_{\text{horizontal}} \oplus \underbrace{TM}_{\text{vertical}} \to \mathbb{R}
$$

Examples

$$
\bullet\ \text{Euclidean space}\ M=\mathbb{R}^N, TM=\mathbb{R}^{2N}, g_{\text{Sasaki}}=g_{\mathbb{R}^{2N}}
$$

Choice of Latent Space

- trees fit into Hyperbolic spaces (*κ <* 0)
- grids fit into Euclidean spaces ($\kappa = 0$)
- cycles fit into Spheres (*κ >* 0)

Idea

Provide several components $M = M_0 \times \ldots \times M_k$ with different curvature to make data feel at home. E.g. Symmetric Spaces \rightsquigarrow decompose into $M = M_{\kappa \leq 0} \times \mathbb{R}^n \times M_{\kappa \geq 0}$. (also simplifies a bunch of other things)

Intuition

Good approximation of main geometric content of the data; denoising of irrelevant curvature.

E.g. with metric MDS \simeq principal curved coordinate analysis

Low-dimensional representation with interpretable geometry, can use geometric tools.

Hamiltonian Single Cell Dynamics ...

Time evolution of a point $p = (x, y) \in TM$ is determined by a Hamiltonian flow

$$
\dot{\gamma}=X_H\;,\;\gamma(0)=p
$$

Here *H* is some Hamiltonian (\simeq energy) and X_H is the associated Hamiltonian vector field defined by

$$
\omega(X_H,\cdot)=dH
$$

Example

- $H(x, v) = \frac{1}{2}g(v, v) \rightsquigarrow$ Geodesic Flow
- $H(x, v) = V(x) \rightsquigarrow$ Waddington's landscape

... and Magnetic Systems

Hamiltonian dynamics depends on choice of symplectic structure

• standard symplectic structure on *T* [∗]*M*

 $\omega_0 = dp \wedge dq$

• deformation by magnetic field $\mu \in \Omega^2(M)$

 $\omega = \omega_0 + \pi^* \mu$

Magnetic fields can lead to **motion on cycles** \rightsquigarrow model for cell cycle?

Summary

- RNA velocity embeddings into Sasakian **Geometry**
- Principal curved coordinate analysis
- Hamiltonian and Magnetic Systems on principal curved coordinates
- many other concepts and ideas from differential geometry can be explored

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Thank you!