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– EPFL TOPOLOGY SEMINAR – 2 APRIL 2026 –

SINGLE CELLS, POPULATION DYNAMICS, AND EULER CHARACTERISTIC PROFILES

Motivation

Cell population dynamics is crucial in:

- Stem cell biology
- Cancer treatment
- Regenerative medicine

Example: Glioblastoma

Glioblastoma tumours (GBM) arise from neural stem cell dynamics 'gone wrong'.

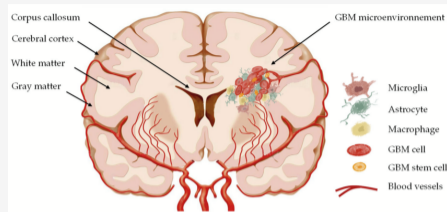
Roughly: dysregulated differentiation process.

High 'stemness' of tumour cells

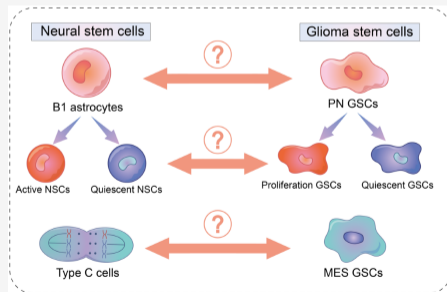
→ therapy resistance, relapse, poor prognosis.

w/ Ana Martin-Vilalba (DKFZ),

Anna Marciniak-Czochra (Heidelberg)

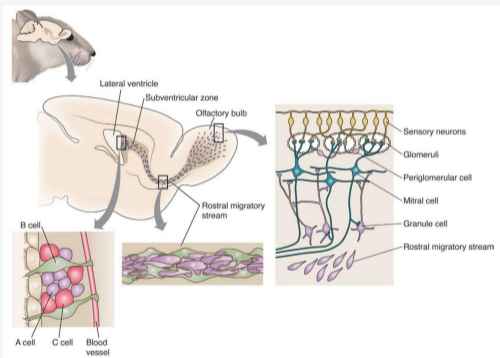


el Kheir et al., 2022



Wang et al., 2021

Model System: Neurogenesis in mature mice



Sanes et al., 2019

(Main) Cell Types

- Quiescent Neural Stem Cells (Q)
- Active Neural Stem Cells (A)
- Differentiated Cells, e.g. Neurons (D)

Questions

- How do cells transition between

$$Q \leftrightarrow A \leftrightarrow D$$

- How do transitions depend on population size (signalling), time (aging), external factors (e.g., inflammation)?
- How do these dynamics change in disease?

Population Dynamics

Compartmental models are determined by:

- Graph (compartments + transitions)
- Transition rates between compartments

$$\frac{dQ}{dt} = -rQ + 2bpA$$

$$\frac{dA}{dt} = rQ - pA$$

$$\frac{dD}{dt} = 2(1-p)bA$$

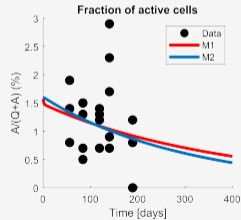
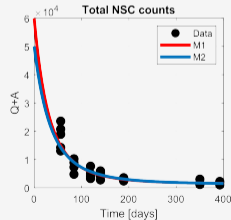
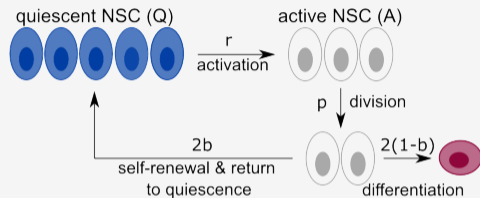
Problem

Population dynamics not identifiable from data.

Many models fit the same population data.

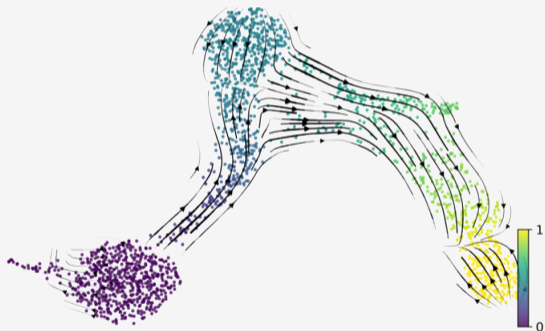
(different graphs, rates, non-linearities, ...)

Model schematic

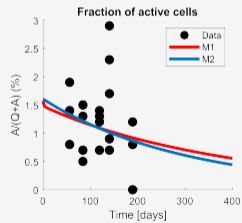
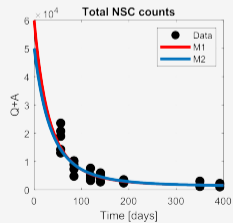
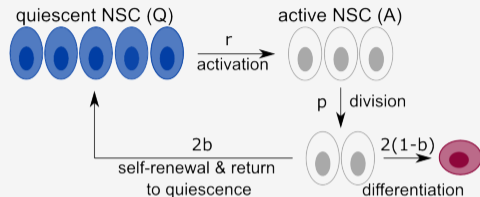


Population Dynamics

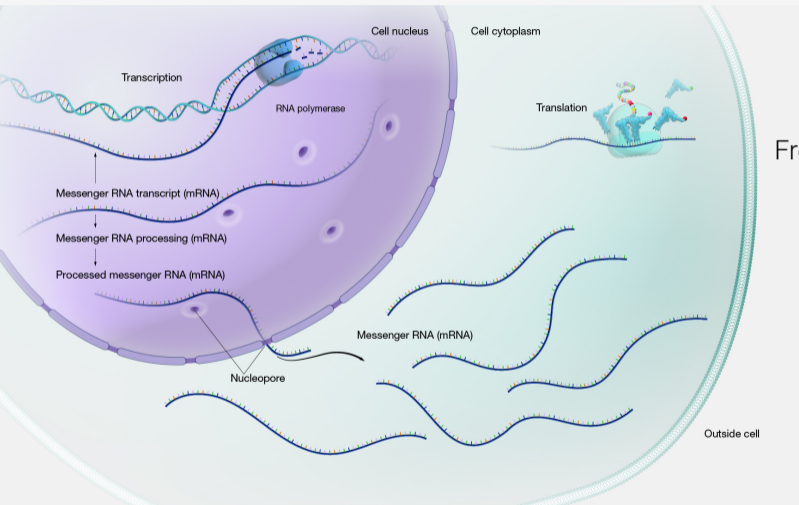
Q: Can single-cell data help?



Model schematic



Single-cell Gene Expression



From code to function

- DNA \rightarrow mRNA \rightarrow proteins
- gene expression \simeq # mRNA snippets
- proxy for cell's current biological state $x_i \in \mathbb{R}^N$

Single-cell dynamics: a minimal picture

1. Cell state dynamics

Each cell can be in one of several cell states

$$z \in \{Q, A, D, \dots\}$$

determines transcription rate $\alpha_{z,g}$ for each gene g

State probability follows a continuous-time Markov chain:

$$\frac{d}{dt}p_z(t) = \sum_{z'} H_{zz'}p_{z'}(t)$$

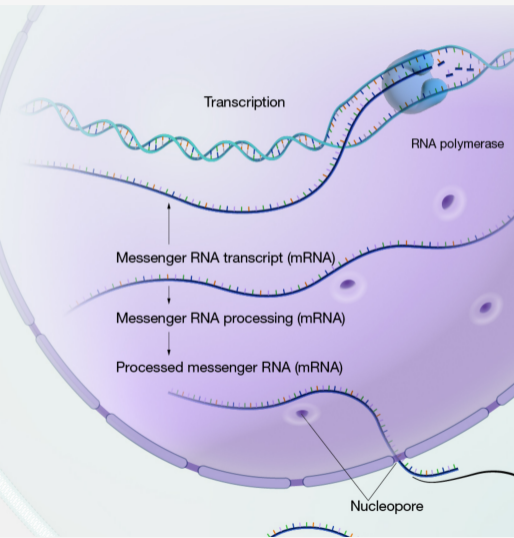
2. Gene transcription dynamics

Gene expression follows a transcription-degradation process:

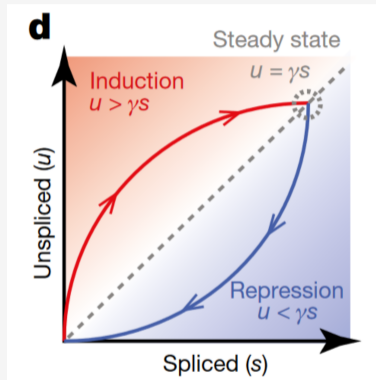
$$\frac{dx_g}{dt} = \alpha_{z(t),g} - \gamma x_g$$

- x_g : expression of gene g
- α_{g,z_t} : transcription rate
- γ : degradation rate

RNA velocity



La Manno, G. et al. (2018) 'RNA velocity of single cells',
Nature, 560(7719), pp. 494–498. Fig 1.



$\rightsquigarrow v_i \in \mathbb{R}^N$ RNA velocity

Single-cell dynamics: a slightly extended picture

1. Cell state dynamics

Each cell can be in one of several cell states

$$z \in \{Q, A, D, \dots\}$$

determines transcription rate $\alpha_{z,g}$ for each gene g

State probability follows a continuous-time Markov chain:

$$\frac{d}{dt}p_z(t) = \sum_{z'} H_{zz'}p_{z'}(t)$$

2. Gene transcription dynamics

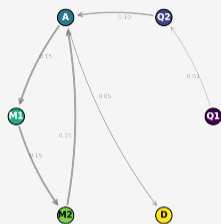
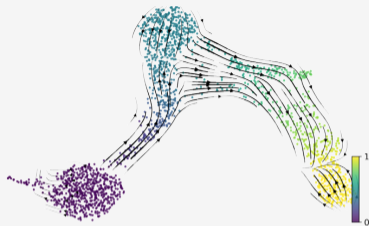
Gene expression follows a transcription-splicing-degradation process:

$$\frac{du_g}{dt} = \alpha_{z(t),g} - \beta u_g$$

$$\frac{ds_g}{dt} = \beta u_g - \gamma s_g$$

- u_g/s_g : unspliced/spliced expression
- α_{g,z_t} : transcription rate
- β : splicing rate
- γ : degradation rate

From single cells to populations



Single-cell level

Continuous-time Markov Chain (CTMC)

(interacting particles / mean field)

$$\frac{d}{dt} \begin{pmatrix} PQ \\ PA \\ PD \end{pmatrix} = \begin{pmatrix} -\lambda_{QA} & \lambda_{AQ} & 0 \\ \lambda_{QA} & -(\lambda_{AQ} + \lambda_{AD}) & \lambda_{DA} \\ 0 & \lambda_{AD} & -\lambda_{DA} \end{pmatrix} \begin{pmatrix} PQ \\ PA \\ PD \end{pmatrix}$$

\xrightarrow{LLN}

Population level

Occupation number ODEs

(non-linear in population sizes)

$$\frac{d}{dt} \begin{pmatrix} Q \\ A \\ D \end{pmatrix} = \begin{pmatrix} -f_{QA} & f_{AQ} & 0 \\ f_{QA} & -(f_{AQ} + f_{AD}) & f_{DA} \\ 0 & f_{AD} & -f_{DA} \end{pmatrix} \begin{pmatrix} Q \\ A \\ D \end{pmatrix}$$

A Hierarchy of Problems

Linking scRNA-seq data to population dynamics requires answering

1. What **compartments/states** can individual cells be in?
2. What **transitions** occur between these states?
For example: can cells move back into (deep) quiescence or do they remain active?
3. What are the **rates** of these transitions?
4. How do rates **depend on** population size, time, external factors?

Problems 1 & 2: Graph structure → Topology

Can we differentiate between candidate graphs using TDA?

Approach: Euler Characteristic Profiles.

with Marta Marszweska (Gdansk, Warsaw), Justyna Signerska-Rynkowska (Gdansk), Pawel Dlotko (Warsaw)

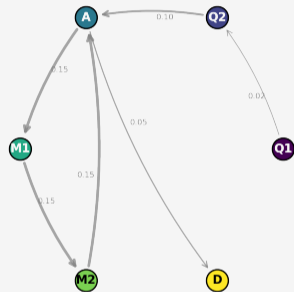
Application Goal: Uncovering Cell State Transitions

The Biological Question

After benchmarking validates the method, we can apply it to answer:

Consider the (Q, A, D) system:

- Does an $A \rightarrow Q2$ transition exist? How about an $A \rightarrow Q1$ transition? Or an $M2 \rightarrow Q1$ transition?
- That is: can cells land in (deep) quiescence after division?



From labeled points to filtered graphs

What We Have (at least in principle)

For each cell

- current gene expression $x_i \in \mathbb{R}^N$
- RNA velocity $v_i \in T_{x_i} \mathbb{R}^N$

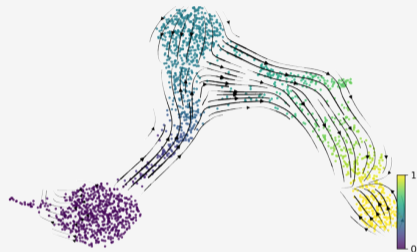
$$X = \{(x_i, v_i)\} \subset T\mathbb{R}^N$$

What We Want

- Graph structure of the Markov chain on cell states

The Key Question

How do we extract the transition graph from X ?



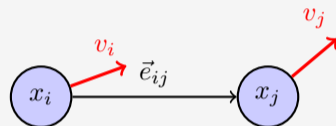
From labeled points to filtered graphs

Construct symmetric kNN graph $\Gamma_{kNN}(\{x_i\})$.

For each edge $(x_i, x_j) \in \Gamma_{kNN}$ set $\vec{e}_{ij} = x_j - x_i$, define

$$a_{ij} = d_{\cos}(\vec{e}_{ij}, v_i), \quad b_{ij} = d_{\cos}(\vec{e}_{ij}, v_j),$$

with cosine distance $d_{\cos}(u, v) = 1 - \frac{u \cdot v}{\|u\| \|v\|} \in [0, 2]$.



Edge bifiltration

$$f(x_i, x_j) = (\min(a_{ij}, b_{ij}), \max(a_{ij}, b_{ij})) \in [0, 2] \times [0, 2]$$

Interpretation

Small filtration \rightarrow pairwise velocity alignment \rightarrow signal of state transition.

From filtered graphs to filtered complexes

For a graph $\Gamma = (V, E)$, its **clique / flag complex** is

$$K(\Gamma) = \{\sigma \subseteq V \mid \{u, v\} \in E \text{ for all } u, v \in \sigma\}.$$

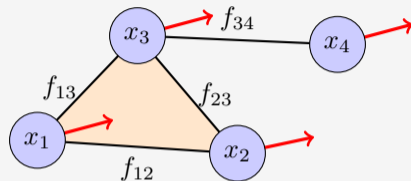
$$(p+1)\text{-clique in } \Gamma \iff p\text{-simplex in } K(\Gamma)$$

Filtration

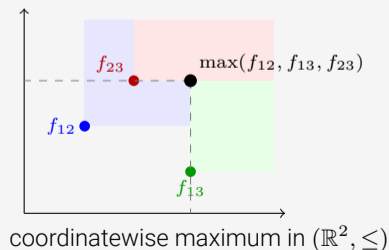
- Vertices: $f(x_i) = (0, 0)$
- Edges: $f(x_i, x_j) = (\min, \max)$
- Higher simplices when all faces are present:

$$f(\sigma) = \max_{(x, x') \subseteq \sigma} f(x, x')$$

$$K_\epsilon(\Gamma) := \{\sigma \in K(\Gamma) \mid f(\sigma) \leq \epsilon = (\epsilon_1, \epsilon_2)\}$$



$$f(\Delta) = \max(f_{12}, f_{13}, f_{23})$$



The Euler Characteristic Profile (ECP)

$$K_{\bullet}(\Gamma) : (P, \leq) \rightarrow (\text{SimpComp}, \subseteq)$$

Applying homology \implies multi-parameter persistence module.


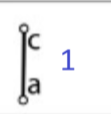
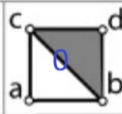
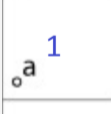
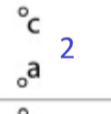
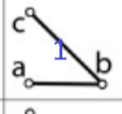


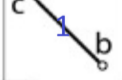
Hard to interpret, hard to compute.

Euler Characteristic Profile

$$ECP : P \rightarrow \mathbb{Z}$$

$$\begin{aligned} (a, b) \mapsto \chi(K_{(a,b)}) &= \sum_{i=0}^n (-1)^i \#\{\sigma \in K_{(a,b)} \mid \dim \sigma = i\} \\ &= \sum_{i=0}^n (-1)^i \text{rk } H_i(K_{(a,b)}) \end{aligned}$$

?? to interpret, embarrassingly easy to compute.

ECP of flag complexes via Bron–Kerbosch

Each simplex σ contributes ± 1 at $f(\sigma)$.

$$ECP = \sum_{\sigma} \phi_{\sigma}, \quad \phi_{\sigma}(\epsilon) = (-1)^{\dim \sigma} \mathbf{1}_{\{\epsilon \geq f(\sigma)\}}$$

Bron–Kerbosch algorithm for ECP

BronKerboschECP(G)

Extend($\emptyset, V, (0, 0)$)

Extend(σ, C, f_{σ})

for each $w \in C$:

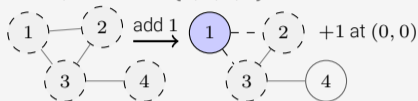
$\sigma' \leftarrow \sigma \cup \{w\}$

$f' \leftarrow \max\{f_{\sigma}, f(v, w) : v \in \sigma\}$

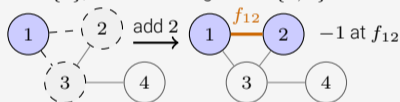
record $(-1)^{\dim \sigma'}$ at f'

Extend($\sigma', C \cap N(w), f'$)

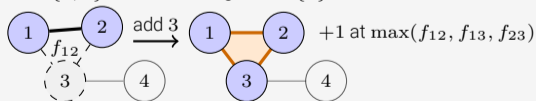
$\sigma = \emptyset$, candidates $\{1, 2, 3, 4\}$



$\sigma = \{1\}$, common neighbours $\{2, 3\}$



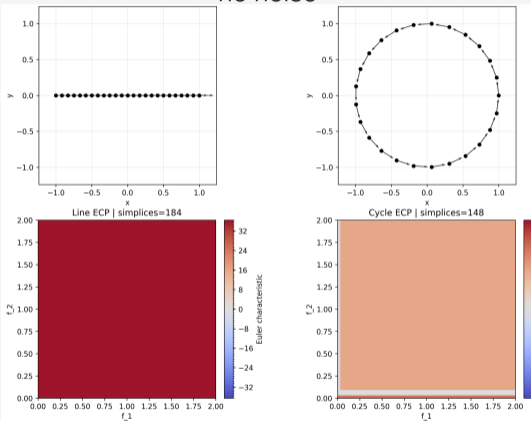
$\sigma = \{1, 2\}$, common neighbours $\{3\}$



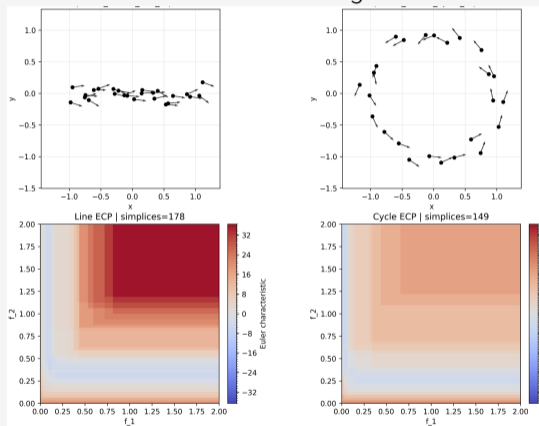
⋮

Stability Experiments

no noise

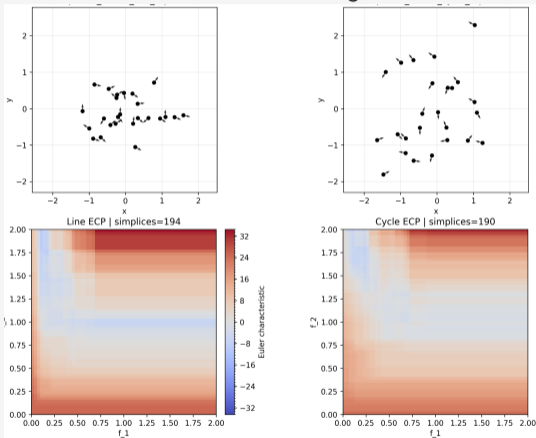


noise $\sim 10\%$ of signal

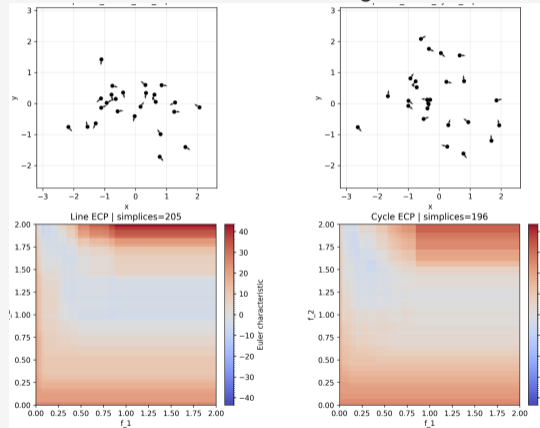


Stability Experiments

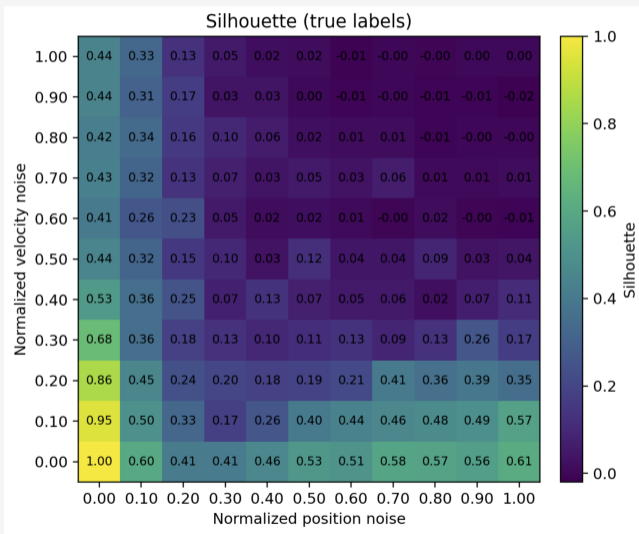
noise \sim 50% of signal



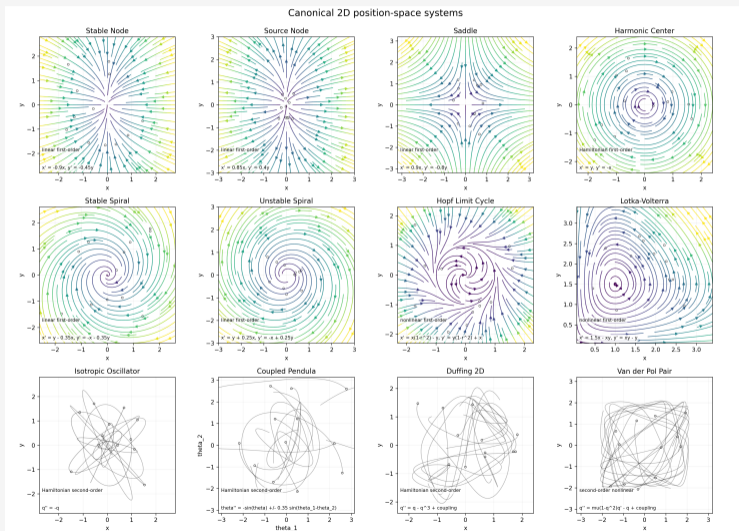
noise \sim 100% of signal



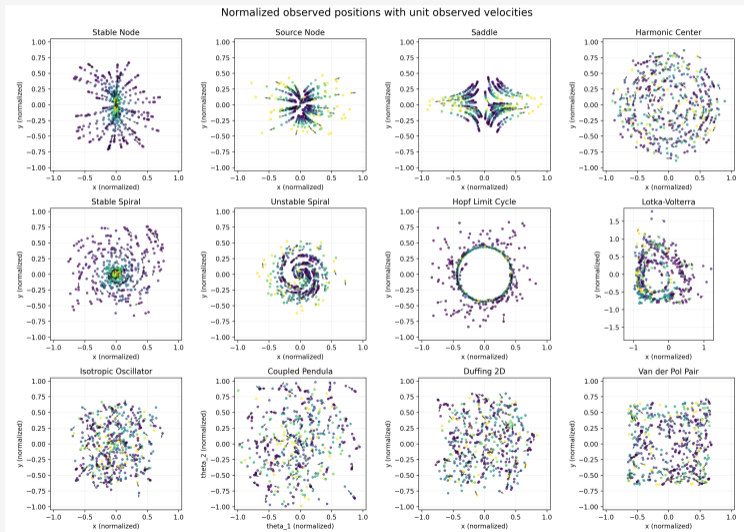
Stability Experiments



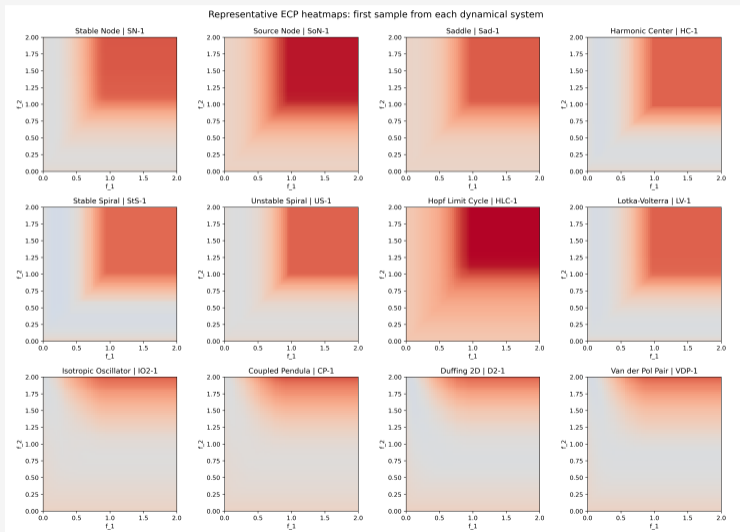
Low-dimensional dynamical systems



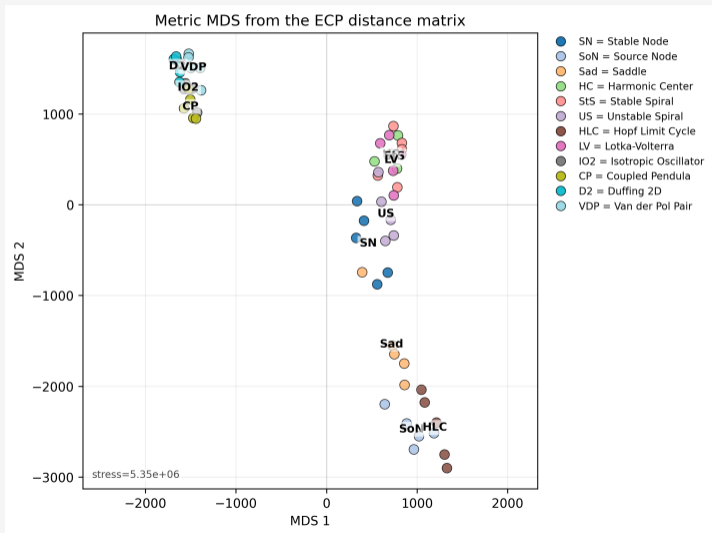
Low-dimensional dynamical systems



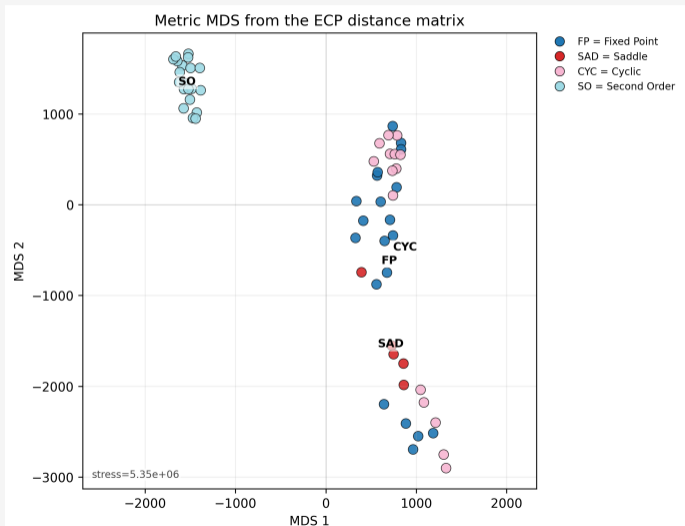
Low-dimensional dynamical systems



Low-dimensional dynamical systems



Low-dimensional dynamical systems



Synthetic Data: A Markov-Modulated Splicing Model

Generate synthetic u/s-counts of single cells using two-level dynamics:

- **Latent state process:**

Continuous-time Markov chain on a state graph

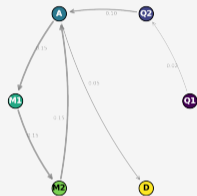
- States z_1, \dots, z_n with probability p_i
- $\frac{d}{dt} p_i = \sum_j H_{ij} p_j$
- Asymmetric transition rates $H_{ij} \neq H_{ji}$, encode directionality

- **Gene expression:**

Standard transcription-splicing-degradation process for cell in state z with state-dependent transcription rate α_z

- $\frac{du}{dt} = \alpha_z - \beta \cdot u$ (transcription + splicing)
- $\frac{ds}{dt} = \beta \cdot u - \gamma \cdot s$ (splicing + degradation)

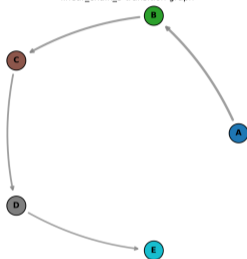
Output: u/s-counts + current state for each cell at time t .



Synthetic scRNA-seq data

Linear Chain

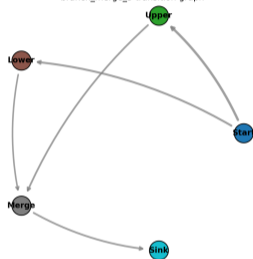
linear_chain_5 transition graph



Underlying five-node transition graphs

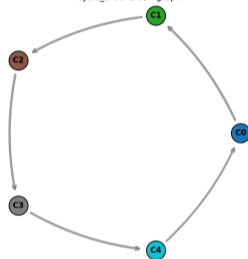
Branch-Merge

branch_merge_5 transition graph



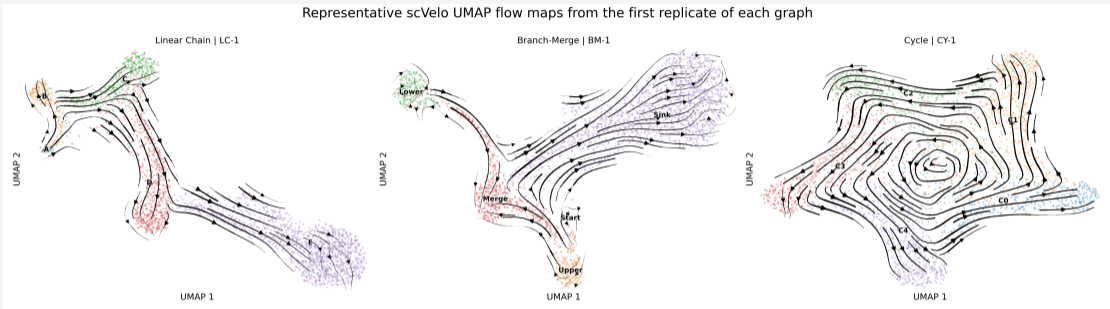
Cycle

cycle_5 transition graph



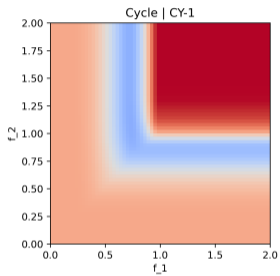
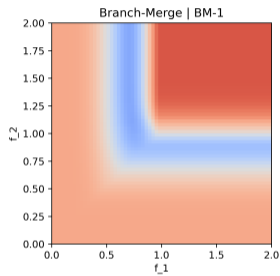
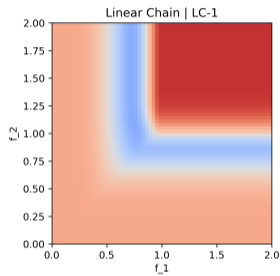
Synthetic scRNA-seq data

Representative scVelo UMAP flow maps from the first replicate of each graph

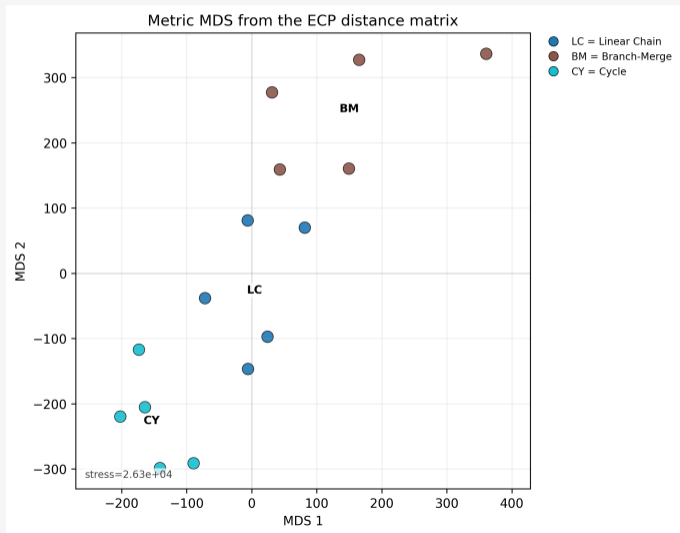


Synthetic scRNA-seq data

Representative ECP heatmaps: first replicate from each five-node graph



Synthetic scRNA-seq data



Current Status and Next Steps

What We Have

- Bifiltered complex construction (kNN + velocity alignment)
- ECP computation for bifiltrations
- synthetic data for arbitrary graphs

Next Steps

1. Proper benchmarking
2. Systematic noise sensitivity analysis
3. high-dimensional data is famously noisy; too noisy for ECP to be useful?
4. RNA velocity is famously unreliable; too unreliable for ECP to be useful?
5. Move beyond classification/clustering; can we recover the ground truth?

Thanks for your attention